



Wolfram|Alpha Step-by-Step Solution

Wolfram|Alpha Input:

STEP 1

Solve $\frac{d^2 y(t)}{dt^2} + 4 y(t) = \cos(a t)$, such that $y(0) = \frac{1}{2}$ and $y'(0) = 0$:

STEP 2

The general solution will be the sum of the complementary solution and particular solution.

Find the complementary solution by solving $\frac{d^2 y(t)}{dt^2} + 4 y(t) = 0$:

STEP 3

Assume a solution will be proportional to $e^{\lambda t}$ for some constant λ .

Substitute $y(t) = e^{\lambda t}$ into the differential equation:

$$\frac{d^2}{dt^2}(e^{\lambda t}) + 4 e^{\lambda t} = 0$$

STEP 4

Substitute $\frac{d^2}{dt^2}(e^{\lambda t}) = \lambda^2 e^{\lambda t}$:

$$\lambda^2 e^{\lambda t} + 4 e^{\lambda t} = 0$$

STEP 5

Factor out $e^{\lambda t}$:

$$(\lambda^2 + 4) e^{\lambda t} = 0$$

STEP 6

Since $e^{\lambda t} \neq 0$ for any finite λ , the zeros must come from the polynomial:

$$\lambda^2 + 4 = 0$$

STEP 7

Solve for λ :

$$\lambda = 2i \text{ or } \lambda = -2i$$

STEP 8

The roots $\lambda = \pm 2i$ give $y_1(t) = c_1 e^{2it}$, $y_2(t) = c_2 e^{-2it}$ as solutions, where c_1 and c_2 are arbitrary constants.

The general solution is the sum of the above solutions:

$$y(t) = y_1(t) + y_2(t) = c_1 e^{2it} + c_2 e^{-2it}$$

STEP 9

Apply Euler's identity $e^{\alpha+i\beta} = e^\alpha \cos(\beta) + i e^\alpha \sin(\beta)$:

$$y(t) = c_1 (\cos(2t) + i \sin(2t)) + c_2 (\cos(2t) - i \sin(2t))$$

STEP 10

Regroup terms:

$$y(t) = (c_1 + c_2) \cos(2t) + i(c_1 - c_2) \sin(2t)$$

STEP 11

Redefine $c_1 + c_2$ as c_1 and $i(c_1 - c_2)$ as c_2 , since these are arbitrary constants:

$$y(t) = c_1 \cos(2t) + c_2 \sin(2t)$$

STEP 12

Determine the particular solution to $\frac{d^2 y(t)}{dt^2} + 4y(t) = \cos(at)$ by variation of parameters:

List the basis solutions in $y_c(t)$:

$$y_{b_1}(t) = \cos(2t) \text{ and } y_{b_2}(t) = \sin(2t)$$

STEP 13

Compute the Wronskian of $y_{b_1}(t)$ and $y_{b_2}(t)$:

$$\mathcal{W}(t) = \begin{vmatrix} \cos(2t) & \sin(2t) \\ \frac{d}{dt}(\cos(2t)) & \frac{d}{dt}(\sin(2t)) \end{vmatrix} = \begin{vmatrix} \cos(2t) & \sin(2t) \\ -2\sin(2t) & 2\cos(2t) \end{vmatrix} = 2$$

STEP 14

Let $f(t) = \cos(at)$:

$$\text{Let } v_1(t) = -\int \frac{f(t)y_{b_2}(t)}{\mathcal{W}(t)} dt \text{ and } v_2(t) = \int \frac{f(t)y_{b_1}(t)}{\mathcal{W}(t)} dt:$$

The particular solution will be given by:

$$y_p(t) = v_1(t) y_{b_1}(t) + v_2(t) y_{b_2}(t)$$

STEP 15

Compute $v_1(t)$:

$$v_1(t) = -\int \frac{1}{2} \cos(at) \sin(2t) dt = -\frac{\cos(t(a-2))}{4(a-2)} + \frac{\cos(t(a+2))}{4(a+2)}$$

STEP 16

Compute $v_2(t)$:

$$v_2(t) = \int \frac{1}{2} \cos(2t) \cos(at) dt = \frac{1}{2} \left(\frac{\sin(t(a-2))}{2(a-2)} + \frac{\sin(t(a+2))}{2(a+2)} \right)$$

STEP 17

The particular solution is thus:

$$y_p(t) = v_1(t) y_{b_1}(t) + v_2(t) y_{b_2}(t) = \cos(2t) \left(-\frac{\cos((a-2)t)}{4(a-2)} + \frac{\cos((a+2)t)}{4(a+2)} \right) + \frac{1}{2} \left(\frac{\sin((a-2)t)}{2(a-2)} + \frac{\sin((a+2)t)}{2(a+2)} \right) \sin(2t)$$

STEP 18

Simplify:

$$y_p(t) = -\frac{\cos(at)}{a^2 - 4}$$

STEP 19

The general solution is given by:

$$y(t) = y_c(t) + y_p(t) = c_1 \cos(2t) + c_2 \sin(2t) - \frac{\cos(at)}{a^2 - 4}$$

STEP 20

Solve for the unknown constants using the initial conditions:

Compute $\frac{dy(t)}{dt}$:

$$\begin{aligned} \frac{dy(t)}{dt} &= \frac{d}{dt} \left(-\frac{\cos(at)}{a^2 - 4} + c_1 \cos(2t) + c_2 \sin(2t) \right) \\ &= \frac{a \sin(at)}{a^2 - 4} - 2c_1 \sin(2t) + 2c_2 \cos(2t) \end{aligned}$$

STEP 21

Substitute $y(0) = \frac{1}{2}$ into $y(t) = -\frac{\cos(at)}{a^2 - 4} + \cos(2t)c_1 + \sin(2t)c_2$:

$$-\frac{1}{a^2 - 4} + c_1 = \frac{1}{2}$$

STEP 22

Substitute $y'(0) = 0$ into $\frac{dy(t)}{dt} = \frac{a \sin(at)}{a^2 - 4} - 2 \sin(2t) c_1 + 2 \cos(2t) c_2$:

$$2 c_2 = 0$$

STEP 23

Solve the system:

$$c_1 = \frac{a^2 - 2}{2(a^2 - 4)}$$

$$c_2 = 0$$

STEP 24

Substitute $c_1 = \frac{a^2 - 2}{2(a^2 - 4)}$ and $c_2 = 0$ into $y(t) = -\frac{\cos(at)}{a^2 - 4} + \cos(2t) c_1 + \sin(2t) c_2$:

Answer:

$$y(t) = \frac{-2 \cos(at) + (a^2 - 2) \cos(2t)}{2(a^2 - 4)}$$

